Yang-Baxter sigma models and Lax pairs arising from kappa-Poincare r-matrices

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References:

A. Borowiec, H. Kyono, J. Lukierski, J. Sakamoto and KY, arXiv: 1511.00404

T. Matsumoto, D. Orlando, S. Reffert, J. Sakamoto and KY, arXiv: 1505.04553



What is Yang-Baxter sigma model?

The recent progress on it

Yang-Baxter sigma model

A systematic way to study integrable deformations of 2D integrable non-linear sigma models, such as principal chiral model (PCM) and symmetric coset models.

Proposed by Klimcik in 2002, and the integrability was shown in 2008. II The existence of Lax pair
$$\begin{split} & -\underline{\text{Yang-Baxter-deformation of PCM}} \qquad [\text{Klimcik, 2002, 2008}] \\ & S = \int d^2 x \, \eta^{\mu\nu} \text{tr}(J_\mu J_\nu) \longrightarrow S^{(\eta)} = \int d^2 x \, \eta^{\mu\nu} \text{tr}\left(J_\mu \, \frac{1}{1 - \eta R} \, J_\nu\right) \\ & J_\mu = g^{-1} \partial_\mu g, \ g \in G \qquad \hline \text{deformation!} \qquad \eta \ : \text{const.} \end{split}$$

Linear op. $R : \mathfrak{g} \longrightarrow \mathfrak{g}$ is related to classical r-matrix via

$$R(X) \equiv \langle r_{12}, 1 \otimes X \rangle = \sum_{i} a_i \langle b_i, X \rangle \quad \text{for } X, a_i, b_i \in \mathfrak{g}$$

where $r_{12} = \sum_{i} a_i \otimes b_i$ satisfies modified classical Yang-Baxter eq. (mCYBE)

<u>— NOTE</u>

- An integrable deformation is specified by a classical r-matrix.
- Given a classical r-matrix, a Lax pair follows automatically.

Recent Progress

[Delduc-Magro-Vicedo, 1309.5850] [Kawaguchi-Matsumoto-KY, 1401.4855]

Yang-Baxter deformations of the AdS₅ x S⁵ superstring

Classical r-matrices have been identified with a lot of gravity solutions, including well-known examples.

EX η -deformations of AdS₅ x S⁵ (New)

 $\gamma\text{-deformations of S^5,}$ $\,$ gravity duals of NC gauge theories, $\,$

Schrödinger spacetimes, dipole backgrounds etc.

Motivated by this progress, as a generalization,

we have considered

Yang-Baxter deformations of 4D Minkowski spacetime.

[Matsumoto-Orlando-Reffert-Sakamoto-KY, 1505.04553]

The content of my talk

1. Yang-Baxter deformations of Minkowski spacetime

T. Matsumoto, D. Orlando, S. Reffert, J. Sakamoto and K.Y., arXiv: 1505.04553

2. Deformed geometries and Lax pairs arising from kappa-Poincare r-matrices

A. Borowiec, H. Kyono, J. Lukierski, J. Sakamoto and K.Y., arXiv: 1511.00404

3. Summary & Discussion

 Yang-Baxter deformations of Minkowski spacetime

T. Matsumoto, D. Orlando, S. Reffert, J. Sakamoto and K.Y., arXiv: 1505.04553

Question

Why do we study Yang-Baxter deformations of Minkowski spacetime?

- There are a lot of backgrounds FACT for which string theories are exactly solved
 - EX Melvin backgrounds, pp-wave backgrounds, other solvable time-dependent backgrounds
 - e.g. [Hashimoto-Sethi, hep-th/0208126] [Spradlin-Takayanagi-Volovich, hep-th/0509036]





Deformations of Minkowski spacetime

Motives

- There is a possibility to unify the already-known solvable backgrounds 1) as Yang-Baxter deformations of Minkowski spacetime.
- By adopting the YB-deformations, new solvable backgrounds may be found. 2)

Yang-Baxter sigma model for 4D Minkowski

picks up vielbeins, avoiding subtlety of the degenerate Killing form.

NOTE the general form of Lax pair has not been constructed yet.

A schematic list of classical r-matrices
(a)
$$r = \text{Poincaré} \otimes \text{Poincaré}$$

1. abelian e.g., $r \sim p_1 \land p_2$, 2. non-abelian e.g., $r \sim p_1 \land n_{12}$,
(b) $r = \text{Poincaré} \otimes \text{non-Poincaré}$
1. abelian e.g., $r \sim n_{12} \land \hat{d}$, 2. non-abelian e.g., $r \sim p_0 \land \hat{d}$,
(c) $r = \text{non-Poincaré} \otimes \text{non-Poincaré}$
1. abelian e.g., $r \sim k_1 \land k_2$, 2. non-abelian e.g., $r \sim k_0 \land \hat{d}$.
The generators of so(2,4): p_{μ} , $n_{\mu\nu}$, \hat{d} , k_{μ}
 $[p_{\mu}, k_{\nu}] = 2(n_{\mu\nu} + \eta_{\mu\nu} \hat{d})$, $[\hat{d}, p_{\mu}] = p_{\mu}$, $[\hat{d}, k_{\mu}] = -k_{\mu}$,
 $[p_{\mu}, n_{\nu\rho}] = \eta_{\mu\nu} p_{\rho} - \eta_{\mu\rho} p_{\nu}$, $[k_{\mu}, n_{\nu\rho}] = \eta_{\mu\nu} k_{\rho} - \eta_{\mu\rho} k_{\nu}$,
 $[n_{\mu\nu}, n_{\rho\sigma}] = \eta_{\mu\sigma} n_{\nu\rho} + \eta_{\nu\rho} n_{\mu\sigma} - \eta_{\mu\rho} n_{\nu\sigma} - \eta_{\nu\sigma} n_{\mu\rho}$.

Classical r-matrices and the associated backgrounds (ide

(identified so far)

-	r-matrix	Type of Twist	Background
Exactly Solvable	$p_{i} \wedge p_{j} \ (i, j = 1, 2, 3)$ $p_{0} \wedge p_{i}$ $(p_{0} + p_{i}) \wedge p_{j} \ (i \neq j)$ $\frac{1}{2}p_{3} \wedge n_{12}$ $\frac{1}{2\sqrt{2}}p_{2} \wedge (n_{01} + n_{13})$ $\frac{1}{2}n_{12} \wedge n_{03}$ $\frac{1}{2}p_{1} \wedge n_{03}$	Melvin Shift Twist Melvin Shift Twist Null Melvin Shift Twist Melvin Twist Melvin Null Twist R Melvin R Twist Melvin Boost Twist	Seiberg-Witten NCOS light-like NC T–dual Melvin Hashimoto–Sethi Spradlin–Takayanagi–Volovich T–dual of Grant space
	$\frac{1}{2\sqrt{2}}(p_0 - p_3) \wedge n_{12}$	Null Melvin Twist	pp-wave
	$\frac{1}{2\sqrt{2}}(\hat{d}-n_{03})\wedge(p_0-p_3)$	Non-Twist	pp-wave Class (b) 2
Integrable	$\begin{bmatrix} \frac{1}{2}\hat{d} \wedge p_0 \end{bmatrix}$	Non-Twist	T-dual of dS_4
	$\frac{1}{2}\hat{d}\wedge p_1$	Non-Twist	T–dual of AdS_4
Integrable?	DJ-type (mCYBE)	Non-Twist	q-deformation (?) Class (b) 2

- These results support the integrability of YB-deformed action.
- Would-be new backgrounds obtained (not mentioned above)



2. Deformed geometries and Lax pairs arising from kappa-Poincare r-matrices

A. Borowiec, H. Kyono, J. Lukierski, J. Sakamoto and K.Y., arXiv: 1511.00404

Kappa-Poincare r-matrix

classical r-matrix: $r = a^{\mu} n_{\mu\nu} \wedge p^{\nu}$ (class (a) 2) a^{μ} : a constant 4D vector

satisfies the modified classical Yang-Baxter eq.

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = \frac{1}{2} (a_{\mu} a^{\mu}) p^{\rho} \wedge n_{\rho\sigma} \wedge p^{\sigma}$$

There are 3 special cases:

$$\kappa$$
 : a real positive const.

- 1. Standard deformation
- 2. Tachyonic deformation
- 3. Light-cone deformation

- $a^{\mu} = (\frac{1}{\kappa}, 0, 0, 0)$: time-like vector
- $a^{\mu} = (0, \frac{1}{\kappa}, 0, 0)$: space-like vector

$$a^{\mu} = \left(\frac{1}{\sqrt{2}\kappa}, 0, 0, -\frac{1}{\sqrt{2}\kappa}\right)$$
 : null vector

The deformed backgrounds for 3 special cases:

1. Standard deformation

(time-like)T-duality

$$ds^{2} = \frac{-(dx^{0})^{2} + dr^{2}}{1 - \hat{\eta}^{2}r^{2}} + r^{2}(d\theta^{2} + \sin^{2}\theta \, d\phi^{2})$$

4D de Sitter space

2. Tachyonic deformation

$$ds^{2} = \frac{dt^{2} + (dx^{1})^{2}}{1 + \hat{\eta}^{2}t^{2}} + t^{2}\cosh^{2}\phi d\theta^{2} - t^{2}d\phi^{2}$$

(space-like) T-duality& double Wick rotation

4D anti de Sitter space

3. Light-cone deformation

$$ds^{2} = -2dx^{+}dx^{-} - \frac{2\hat{\eta}^{2}r^{2}}{\cosh^{2}(\hat{\eta}x^{+})}(dx^{+})^{2} + (dr)^{2} + r^{2}d\theta^{2}$$

4D time-dependent pp-wave

A list of classical r-matrices and backgrounds

	<i>r</i> -matrix	Type of Twist	Background
lass ($p_i \wedge p_j \ (i, j = 1, 2, 3)$	Melvin Shift Twist	Seiberg-Witten
	$p_0 \wedge p_i$	Melvin Shift Twist	NCOS
	$(p_0 + p_i) \land p_j \ (i \neq j)$	Null Melvin Shift Twist	light-like NC
	$rac{1}{2}p_3\wedge n_{12}$	Melvin Twist	T–dual Melvin
	$\frac{1}{2\sqrt{2}}p_2 \wedge (n_{01} + n_{13})$	Melvin Null Twist	Hashimoto–Sethi
	$\frac{1}{2}n_{12} \wedge n_{03}$	R Melvin R Twist	Spradlin-Takayanagi-Volovich
	$\frac{1}{2}p_1 \wedge n_{03}$	Melvin Boost Twist	T–dual of Grant space
	(D) $2 \frac{1}{2\sqrt{2}} (p_0 - p_3) \wedge n_{12}$	Null Melvin Twist	pp-wave
	$\frac{1}{2\sqrt{2}}(\hat{d}-n_{03})\wedge(p_0-p_3)$	Non-Twist	pp-wave
	$\frac{1}{2}\hat{d} \wedge p_0$	Non-Twist	T-dual of dS_4
	$\underline{\frac{1}{2}\hat{d}\wedge p_1}$	Non-Twist	T–dual of AdS_4
	DJ-type (mCYBE)	Non-Twist	q-deformation (?)

As a result, this part has been reproduced by different classical r-matrices!

(class (a) 2.)

What is the reasoning behind this coincidence?

Lax pair for general kappa-deformations

$$- \underline{\text{Lax pair}}$$

$$\mathcal{L}_{\pm} = P_0(J_{\pm}) + \lambda^{\pm 1} \left[P(J_{\pm}) + P'(J_{\pm}) \right]$$

$$-a_{\mu} a^{\mu} \eta^2 \lambda^{\pm 1} \left[P(J_{\pm}) - P'(J_{\pm}) \right]$$

 λ : spectral parameter

Here we have introduced a deformed current

$$J_{\pm} \equiv \frac{1}{1 \mp 2\eta R_g \circ P} A_{\pm}$$

and 2 extra projections: (P is utilized in the classical action)

$$P'(x) \equiv \sum_{\mu=0}^{3} n_{\mu 5} \frac{\operatorname{Tr}(n_{\mu 5} x)}{\operatorname{Tr}(n_{\mu 5} n_{\mu 5})}, \quad P_0(x) \equiv \frac{1}{2} \sum_{\mu,\nu=0}^{3} n_{\mu\nu} \frac{\operatorname{Tr}(n_{\mu\nu} x)}{\operatorname{Tr}(n_{\mu\nu} n_{\mu\nu})}$$

NOTE: the associated ∞ -dim. symmetry has not been clarified yet.

NOTE2: the Lax pair can be constructed for the class (a). [Kyono-Sakamoto-KY, to appear]

3. Summary & Discussion

<u>Summary</u>



A lot of well-known backgrounds have been reproduced.

[Matsumoto, Orlando, Reffert, Sakamoto and KY, 1505.04553]



Discussion

Infinite-dim. algebras? SUSY? New backgrounds? Integrability?

Yang-Baxter deformations of other 4D geometries

EX Nappi-Witten model

2D Poincare alg. with a center

Yang-Baxter invariance

[Kyono-KY, 1511.00404]

Question: Are pp-wave backgrounds YB-invariant in general?



The low-energy behavior of the gauge-theory duals of YB-deformed AdS₅ x S⁵ may be determined universally.



Low-energy excited states of spin chain are universal?

Back up

Coset construction of Poincare AdS₅

AdS₅ is represented by a coset: $AdS_5 = SO(2,4)/SO(1,4)$

Here we will use the following notation:

4D gamma matrices:

$$\gamma_{\mu} \ (\mu = 0, 1, 2, 3), \quad \gamma_{5} = -i\gamma_{0}\gamma_{1}\gamma_{2}\gamma_{3}$$

$$n_{\mu\nu} \equiv \frac{1}{4}[\gamma_{\mu}, \gamma_{\nu}], \quad n_{\mu5} \equiv \frac{1}{4}[\gamma_{\mu}, \gamma_{5}]$$

Lie algebras

Lie algebra of SO(2,4): $\mathfrak{so}(2,4) = \operatorname{span}_{\mathbb{R}} \{ \gamma_{\mu}, \gamma_{5}, n_{\mu\nu}, n_{\mu5} \}$ Lie algebra of SO(1,4): $\mathfrak{so}(1,4) = \operatorname{span}_{\mathbb{R}} \{ n_{\mu\nu}, n_{\mu5} \}$

Then, by using the left-invariant 1-form: $A \equiv g^{-1} dg$,

one can compute the metric:

$$ds^2 = g_{MN} dx^M dx^N = \operatorname{Tr}(A\overline{P}(A))$$

where the projection is defined as

(respecting the grading property)

$$\overline{P}(x) \equiv \frac{1}{4} \left[-\gamma_0 \operatorname{Tr}(\gamma_0 x) + \sum_{i=1}^3 \gamma_i \operatorname{Tr}(\gamma_i x) + \gamma_5 \operatorname{Tr}(\gamma_5 x) \right]$$

Finally, we obtain the usual expression:

$$ds^{2} = \frac{-(dx^{0})^{2} + \sum_{i=1}^{3} (dx^{i})^{2} + dz^{2}}{z^{2}}$$

Coset construction of 4D Minkowski spacetime

The group element:

$$g = \exp\left[p_{\mu}x^{\mu}\right]$$

e.g., a slice of
$$\operatorname{AdS}_5$$
 with $z=1$

Instead of \overline{P} , we will use the following projection:

$$P(x) \equiv \frac{1}{4} \left[-\gamma_0 \operatorname{Tr}(\gamma_0 x) + \sum_{i=1}^3 \gamma_i \operatorname{Tr}(\gamma_i x) \right] \qquad \longleftarrow \qquad \begin{array}{c} \gamma_5 \text{ -dependence} \\ \text{ is dropped off.} \end{array}$$

This P may be seen as a map from $\,p_{\mu}$ to a ``dual'' basis $\,\gamma_{\mu}$'s $\,$

(:)
$$\operatorname{Tr}(p_{\mu}\gamma_{\nu}) = \eta_{\mu\nu}$$

$$\mathfrak{iso}(1,3) = \operatorname{span}_{\mathbb{R}}\{p_{\mu}, n_{\mu\nu}\} \iff \mathfrak{iso}^{*}(1,3) = \operatorname{span}_{\mathbb{R}}\{\gamma_{\mu}, n_{\mu\nu}\}$$

NOTE: This step is quite important because $\operatorname{Tr}(p_{\mu}p_{\nu}) = 0$!

Finally, the 4D Minkowski metric is reproduced as

$$ds^{2} = \operatorname{Tr}(AP(A)) = -(dx^{0})^{2} + \sum_{i=1}^{3} (dx^{i})^{2}$$

A schematic picture for a classical r-matrix of the 2nd class





4D Minkowski spacetime is embedded into 5D AdS space.

The 4D slice is deformed by a classical r-matrix

Example 1: A Melvin background

classical r-matrix:
$$r=rac{1}{2}p_3\wedge n_{12}$$
 Class (a) 1.

With a coordinate transformation, $x^1 = r \cos \theta$, $x^2 = r \sin \theta$

the metric and B-field are obtained as

$$ds^{2} = -(dx^{0})^{2} + dr^{2} + \frac{r^{2}d\theta^{2} + (dx^{3})^{2}}{1 + \eta^{2}r^{2}},$$

$$B = \frac{\eta r^{2}}{1 + \eta^{2}r^{2}}d\theta \wedge dx^{3}$$

This result nicely agrees with the known background.

[Gibbons-Maeda, 1988] [Tseytlin, 1994] [Hashimoto-Thomas, 2004]

Note: the dilaton is fixed by imposing that the 1-loop β function vanishes,

$$\Phi = -\frac{1}{2}\log(1+\eta^2 r^2)$$

Example 2: T-dual of 4D de Sitter space

classical r-matrix:
$$r=rac{1}{2}\hat{d}\wedge p_0$$
 Class (b) 2.

Then the metric and B-field are obtained as

$$ds^{2} = \frac{-(dx^{0})^{2} + dr^{2}}{1 - \eta^{2}r^{2}} + r^{2}\sin^{2}\theta d\phi^{2} + r^{2}d\theta^{2},$$

$$B = \frac{\eta r}{1 - \eta^{2}r^{2}}dx^{0} \wedge dr \quad \longrightarrow \quad \text{Total derivative}$$

where we have performed a coordinate transformation

$$x^1 = r \cos \phi \sin \theta$$
, $x^2 = r \sin \phi \sin \theta$, $x^3 = r \cos \theta$

Then by performing a T-duality for the x⁰-direction, the metric is rewritten as

$$ds^{2} = (dr + \eta r \, dx^{0})^{2} - (dx^{0})^{2} + r^{2}(d\theta^{2} + \sin^{2}\theta \, d\phi^{2}).$$

By performing a further coordinate transformation

$$x^{0} = t - \frac{1}{2\eta} \log(\eta^{2} r^{2} - 1),$$

we obtain the metric of 4D de Sitter space

$$ds^{2} = -(1 - \eta^{2}r^{2})dt^{2} + \frac{dr^{2}}{1 - \eta^{2}r^{2}} + r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2})$$

NOTE: There exists a cosmological horizon at $r = 1/\eta$.

Comments:

- The Lax pair has not been constructed for the general form of the deformed action, but this case should be classically integrable.
- 2) The B-field vanishes and the RR-flux should be turned on, but it would be complex.